

ROTARY AXIS SIGNALS

Rotate Magazine to called tool position = CW / CCW
To rotate CW = SetBit(Rotate_ON) & ClearBit(Rotate_CCW)
To rotate CCW = SetBit(Rotate_ON) & SetBit(Rotate_CCW)
- INDEX sensor – !ReadBit(INDEX) – after counting & in position state LO
Should stop magazine motor = ClearBit(Rotate_ON) & ClearBit(Rotate_CCW)

TOP VIEW

