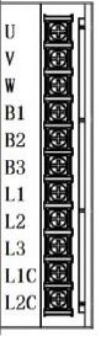
	V	Motor power line terminal	Must be connected with U, V, W, PE terminals of the motor correspondingly Note: PE is the terminal on the metal radiator of the driver.
	W		
	PE		
	U	Motor power line terminal	It must be connected correspondingly with the U, V, W, PE terminals of the motor; Note: PE is the connection terminal on the metal radiator of the driver.
Strong current terminal set 	V		
	W		
	PE	Brake resistor terminal	When using the internal braking resistor, you need to short-circuit B2 and B3; when using the external braking resistor, please disconnect B2 and B3, and connect the braking resistor between B1 and B2; External braking resistor selection and parameter setting Refer to "5.8 Brake Resistor Setting", otherwise the drive may be damaged.
	B1		
	B2		
	B3	power supply input	Connect single-phase or three-phase AC 220V; if connecting single-phase AC 220V, please connect between L1 and L2;
	L1		
	L2		
	L3	Control power input	Connect to single-phase AC 220V;
	L1C		
	L2C		
Low-speed command pulse sequence input	3	PULS+	Select low-speed or high-speed pulse input by parameter PA44; set command pulse input mode by parameter PA14: PA14=0 (default state): pulse/direction; PA14=1: CCW/CW; PA14=2: A/B quadrature pulse. Note: When the external low-speed pulse train voltage is 12V or 24V, replace PULS+ with OPC1, and replace SIGN+ with OPC2.
	4	PULS-	
	5	SIGN+	
	6	SIGN-	
	1	OPC1	
	2	OPC2	
	44	PULSH+	
	45	PULSH-	
High-speed command pulse train input	46	SIGNH+	
	47	SIGNH-	